國立臺北大學自然資源與環境管理研究所 九十九學年度第二學期

『環境系統分析』課程講義 (五、六)

進度:不確定性分析與隨機規劃 Uncertainty Analysis and Stochastic Programming

• PROBABILITY THEORY, STOCHASTIC PROCESS AND RANDOM FIELD

Deterministic vs. Stochastic Systems

- ⇒ Vagueness, Uncertainty and 'Stochasticity'
- ⇒ Possibility, Likelihood, and Probability
- □ Probability Theory
 - ⇒ The Axioms of Probability
 - ⇒ Random Variables: Discrete and Continuous
 - ⇒ Statistics (Moments) of a Random Variable: Expected Value, Variance, ... etc.
 - ⇒ Multiple Random Variables: Multivariate Statistics => Covariances
 - ⇒ Distribution: Probability Density Function, Cumulated Distribution Function
 - ⇒ Conditional Probability and Baye's Theorem => Bayesian Decision Analysis

□ Normal Distribution

- ⇒ Two-Parameter Distribution: Location and Dispersion => Mean and Variance
- ⇒ Standardization and *t*-Distribution
- ⇒ Confidence Interval and Standard Deviation
- ⇒ Multivariate Gaussian Distribution
- □ Stochastic Process
 - ⇒ Serial Random Variables: Temporal, Spatial, Spatio-Temporal Stochastic Processes
 - ⇒ Serial Correlation => Deterministic Term (Trend) + Disturbance (Noise)
 - ⇒ Poisson Process, Markov's Chains, and Random Walks
- □ Random Field
 - ⇒ Random Variables Distributed ('Regionalized') in Space
 - ⇒ Spatial Variability (Correlation) => Trend + Disturbance
 - ⇒ Geostatistics: Kriging (Simple, Ordinary, Universal...) => GIS

• STOCHASTIC PROGRAMMING

- □ Uncertainty Analysis
 - ⇒ Mathematical (Quantitative) Analyses Related to the Uncertainties about 'Systems'
 - ⇒ System Uncertainties: Uncertainties about Measurement, Modeling, and Parameters
- Uncertainties Related to Mathematical Programming Systems
 - Modeling Uncertainties: Assumptions, Objective Functions, and Constraints
 Mathematical Program with Recourse: Multi-Stage Stochastic Programming
 - ⇒ Uncertainties 'Embedded' in Decision Variables: Fuzziness, Grey Information...
 - •Intervals or Specified Ranges => Grey Numbers => Grey Programming
 - •Degree of Set Membership => Fuzzy Set => Fuzzy Programming
 - ⇒ Uncertainties about Model Parameters: Coefficients of Objective Function, RHS, A_{ij}

- •Parameters (Coefficients) of the Optimization Model are Random Variables
- •Treat Decision Variables as 'Deterministic Variables' to be determined
- Probabilistic Constraints => Chance-Constrained Programming
- □ Other Considerations
 - ⇒ Stochastic Dynamic Programming and Markov Decision Process
 - ⇒ Optimal Control and System Dynamics
- TWO-STAGE STOCHASTIC PROGRAMMING WITH RECOURSE
 - □ What is "recourse"? "Wait-and-See"?
 - \Rightarrow Recourse is the ability to take corrective action after a random event has taken place.
 - $\hfill\square$ Scenarios and Stages
 - ⇒ Deterministic Equivalent => Expected-Value Formulation
 - □ An Example (<u>http://wiki.mcs.anl.gov/NEOS/index.php/Stochastic_Programming</u>)

• CHANCE CONSTRAINED PROGRAMMING

- □ What are Chance Constraints?
- □ Significance Level => System Reliability
- □ Row Independence => Independently and Identically Distributed (iid)
- □ Right-Hand-Side Random => Univariate Normal Distribution
- □ Technical Coefficients Random => Multivariate Normal Distribution
- □ Row Dependence => Joint Chance Constraint (relatively complicated!)

Chance Constraints:
$$p\left(\sum_{j=1}^{n} a_{ij} \cdot x_j \propto b_i\right) \ge 1 - \alpha_i; \quad \forall i = 1, \dots m$$

(1)RHS b_i Random: Univariate probability distribution of b_i

i.
$$\alpha \equiv \ge$$

 $p\left(\sum_{j=1}^{n} a_{ij} \cdot x_j \ge b_i\right) \ge 1 - \alpha_i \Rightarrow p\left(b_i \le \sum_{j=1}^{n} a_{ij} \cdot x_j\right) \ge 1 - \alpha_i \Rightarrow F(b_i = \sum a_{ij}x_j) \ge 1 - \alpha_i$
ii. $\alpha \equiv \le$

$$p\left(\sum_{j=1}^{n} a_{ij} \cdot x_{j} \le b_{i}\right) \ge 1 - \alpha_{i} \Longrightarrow p\left(b_{i} \ge \sum_{j=1}^{n} a_{ij} \cdot x_{j}\right) \ge 1 - \alpha_{i} \Longrightarrow 1 - F(b_{i} = \sum a_{ij}x_{j}) \ge 1 - \alpha_{i}$$

(2)Technical Coefficients a_{ij} Random: Multivariate probability distribution of $\sum a_{ij}x_j$

⇒ Variance-Covariance Matrix: Positively definite (symmetric) matrix

- HOMEWORK #3 (2011/04/13 Due)
 - 1. Suppose that the third constraint of the Prototype Example (the Glass Production at Wyndor Co.) in Hillier and Lieberman (2003) is a chance constraint (RHS random), please construct the deterministic equivalent of the stochastic programming model.
 - 2. Suppose that the RHS of the third constraint is a random number with normal distribution of $b_3 \rightarrow N$ (18, 3²). Please use What'sBest and AIMMS to solve the deterministic equivalent model and compare the objective values with respect to the variations of significance levels of 0.5%, 1%, 5%, and 10%.