國立臺北大學自然資源與環境管理研究所 105 學年度第二學期『環境系統分析專題』

課程講義(05): 動態規劃與目標規劃 Dynamic Programming and Goal Programming

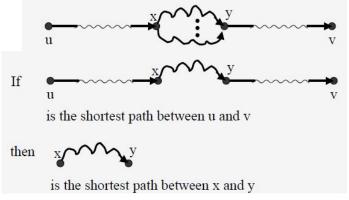
Algorithms - Chapter 6: Dynamic Programming (http://www.cs.berkeley.edu/~vazirani/algorithms/chap6.pdf)
Algorithms - Dynamic Programming (http://www.csie.ntnu.edu.tw/~u91029/DynamicProgramming.html)
Data Clustering and Pattern Recognition - Dynamic Programming 動態規劃

Research Gate - An Introduction to Goal Programming

Linear Optimization - Handouts - Goal Programming

• INTRODUCTION TO DYNAMIC PROGRAMMING

- □ Dynamic Programming = Divide and Conquer + Memoization
- □ No Specific Forms or Formulations=> Principle of Optimality
- ☐ Terminology: Stage, State, Decision, Return, Recursive Equation
- □ Dynamic programming is a technique for solving problems with a recursive structure with the following characteristics:
 - ⇒ Optimal substructure (principle of optimality): An optimal solution to a problem can be decomposed into optimal solutions for sub-problems.
 - \Rightarrow A small number of sub-problems: The total number of sub-instances to be solved is small.
 - ⇒ Overlapping sub-problems: During the computation same instances are referred to over and over again.



☐ An Example of Dynamic Programming: The Shortest Path Problem

GOAL PROGRAMMING

- □ Criteria for Decision-Making: Attribute, Objective, Target, and Goal
- □ Multiple Criteria Decision Making: Multiple Attribute and Multiobjective
- □ Classification of Goal Programming: Non-Preemptive vs. Preemptive
- □ Non-Preemptive Goal Programming
 - ⇒ Complementary relationship
 - ⇒ One-sided vs. Two-sided
- □ Preemptive Goal Programming or Lexicographic GP
- □ Drawbacks: Normalization and Weighting; Pareto Optimality?
- ☐ An Example of Dynamic Programming: Expansion of Production Lines