

# 國立臺北大學自然資源與環境管理研究所

## 九十七學年度第二學期

### 『環境系統分析』課程講義 (四-1)

#### 進度：整數規劃、網路模式與專案管理

#### ● INTEGER PROGRAMMING

- Integer Programming with Network Formulations
  - ⇒ Transportation Problem (Hillier and Lieberman, p.356)
  - ⇒ Assignment Problem (Hillier and Lieberman, p.384)
- Facility Siting Systems (Location Theory or Location Analysis)
  - ⇒ Location Set Covering Problem
  - ⇒ Plant Location Problem
- Solution Technique and Software Packages for IP
  - ⇒ Branch and Bound; Cutting Plane
  - ⇒ Packages: LINGO => @GIN, @BIN; GAMS => RMIP, MIP; What'sBest!

#### ● NETWORK MODEL

- Introduction => c.f.: Continuous Mathematical Programming
- Terminology: Node (Vertex), Arc (Link), Path, and Graph (Tree); Flow and Direction
- Classical Network Programming Models (Hillier and Lieberman, 2001, Chap.9)
  - ⇒ Shortest-Path Problem; Minimum Spanning Tree Problem
  - ⇒ Maximum Flow Problem; Minimum Cost Flow Problem
- Other Models: Traveling Salesman Problem

#### ● REVIEW OF PROBABILITY THEORY AND STOCHASTIC PROCESSES

##### □ The Axioms of Probability

設隨機事件的樣本空間為  $\Omega$ ，對於  $\Omega$  中的每一個事件  $A$ ，都有實函數  $P(A)$ ，滿足：

1. 非負性： $P(A) \geq 0$ ；
2. 規範性： $P(\Omega) = 1$
3. 可加性：對  $n$  個兩兩互不相容的事件  $A_1, \dots, A_n$  有：
$$\sum_{i=1}^n P(A_i) = P\left(\bigcup_{i=1}^n A_i\right)$$

任意一個滿足上述條件的函數  $P$  都可以作為樣本空間  $\Omega$  的機率函數，稱函數值  $P(A)$  為  $\Omega$  中事件  $A$  的機率。

- Random Variables: Discrete and Continuous
- Statistics (Moments) of a Random Variable: Expected Value, Variance, ...etc.

#### ● HOMEWORK #2 (3/31/2009 Due)

1. Use What'sBest to solve Hillier and Lieberman (2001) Problem 12.4-8.
2. Use MS-Project to solve Hillier and Lieberman (2001) Problem 10.3-1 (a)&(b). Hand in the MS-Project (\*.mpp) file with the Gantt Chart (indicating Critical Path) and the Arrow Diagram drawn.