

國立臺北大學自然資源與環境管理研究所

九十七學年度第二學期

『環境系統分析』課程講義（五、六）

進度：不確定性分析與隨機規劃

● PROBABILITY THEORY, STOCHASTIC PROCESS AND RANDOM FIELD

- Deterministic vs. Stochastic Systems
 - ⇒ Vagueness, Uncertainty and ‘Stochasticity’
 - ⇒ Possibility, Likelihood, and Probability
- Probability Theory
 - ⇒ The Axioms of Probability
 - ⇒ Random Variables: Discrete and Continuous
 - ⇒ Statistics (Moments) of a Random Variable: Expected Value, Variance, ...etc.
 - ⇒ Multiple Random Variables: Multivariate Statistics => Covariances
 - ⇒ Distribution: Probability Density Function, Cumulated Distribution Function
 - ⇒ Conditional Probability and Baye’s Theorem => Bayesian Decision Analysis
- Normal Distribution
 - ⇒ Two-Parameter Distribution: Location and Dispersion => Mean and Variance
 - ⇒ Standardization and t -Distribution
 - ⇒ Confidence Interval and Standard Deviation
 - ⇒ Multivariate Gaussian Distribution
- Stochastic Process
 - ⇒ Serial Random Variables: Temporal, Spatial, Spatio-Temporal Stochastic Processes
 - ⇒ Serial Correlation => Deterministic Term (Trend) + Disturbance (Noise)
 - ⇒ Poisson Process, Markov’s Chains, and Random Walks
- Random Field
 - ⇒ Random Variables Distributed (‘Regionalized’) in Space
 - ⇒ Spatial Variability (Correlation) => Trend + Disturbance
 - ⇒ Geostatistics: Kriging (Simple, Ordinary, Universal...) => GIS

● STOCHASTIC PROGRAMMING

- Uncertainty Analysis
 - ⇒ Mathematical (Quantitative) Analyses Related to the Uncertainties about ‘Systems’
 - ⇒ System Uncertainties: Uncertainties about Measurement, Modeling, and Parameters
- Uncertainties Related to Mathematical Programming Systems
 - ⇒ Modeling Uncertainties: Assumptions, Objective Functions, and Constraints
 - Mathematical Program with Recourse: Multi-Stage Stochastic Programming
 - ⇒ Uncertainties ‘Embedded’ in Decision Variables: Fuzziness, Grey Information...
 - Intervals or Specified Ranges => Grey Numbers => Grey Programming
 - Degree of Set Membership => Fuzzy Set => Fuzzy Programming
 - ⇒ Uncertainties about Model Parameters: Coefficients of Objective Function, RHS, A_{ij}

- Parameters (Coefficients) of the Optimization Model are Random Variables
 - Treat Decision Variables as ‘Deterministic Variables’ to be determined
 - Probabilistic Constraints => Chance-Constrained Programming
 - Other Considerations
 - ⇒ Stochastic Dynamic Programming and Markov Decision Process
 - ⇒ Optimal Control and System Dynamics
 - TWO-STAGE STOCHASTIC PROGRAMMING WITH RECOURSE
 - What is “recourse”? “Wait-and-See”?
 - ⇒ Recourse is the ability to take corrective action after a random event has taken place.
 - Scenarios and Stages
 - ⇒ Deterministic Equivalent => Expected-Value Formulation
 - [An Example](http://wiki.mcs.anl.gov/NEOS/index.php/Stochastic_Programming) (http://wiki.mcs.anl.gov/NEOS/index.php/Stochastic_Programming)
 - CHANCE CONSTRAINED PROGRAMMING
 - What are Chance Constraints?
 - Significance Level => System Reliability
 - Row Independence => Independently and Identically Distributed (iid)
 - Right-Hand-Side Random => Univariate Normal Distribution
 - Technical Coefficients Random => Multivariate Normal Distribution
 - Row Dependence => Joint Chance Constraint (relatively complicated!)
- Chance Constraints: $p\left(\sum_{j=1}^n a_{ij} \cdot x_j \geq b_i\right) \geq 1 - \alpha_i; \quad \forall i = 1, \dots, m$
- (1) RHS b_i Random: Univariate probability distribution of b_i
- i. $\alpha \equiv \geq$
- $$p\left(\sum_{j=1}^n a_{ij} \cdot x_j \geq b_i\right) \geq 1 - \alpha_i \Rightarrow p\left(b_i \leq \sum_{j=1}^n a_{ij} \cdot x_j\right) \geq 1 - \alpha_i \Rightarrow F(b_i = \sum a_{ij} x_j) \geq 1 - \alpha_i$$
- ii. $\alpha \equiv \leq$
- $$p\left(\sum_{j=1}^n a_{ij} \cdot x_j \leq b_i\right) \geq 1 - \alpha_i \Rightarrow p\left(b_i \geq \sum_{j=1}^n a_{ij} \cdot x_j\right) \geq 1 - \alpha_i \Rightarrow 1 - F(b_i = \sum a_{ij} x_j) \geq 1 - \alpha_i$$
- (2) Technical Coefficients a_{ij} Random: Multivariate probability distribution of $\sum a_{ij} x_j$
- ⇒ Variance-Covariance Matrix: Positively definite (symmetric) matrix
- HOMEWORK #3 (04/09/2009 Due)
 1. Suppose that the third constraint of the Prototype Example (the Glass Production at Wyndor Co.) in Hillier and Lieberman (2003) is a chance constraint (RHS random), please construct the deterministic equivalent of the stochastic programming model.
 2. Suppose that the RHS of the third constraint is a random number with normal distribution of $b_3 \rightarrow N(18, 3^2)$. Please use What'sBest and GAMS to solve the deterministic equivalent model and compare the objective values with respect to the variations of significance levels of 0.5%, 1%, 5%, and 10%.